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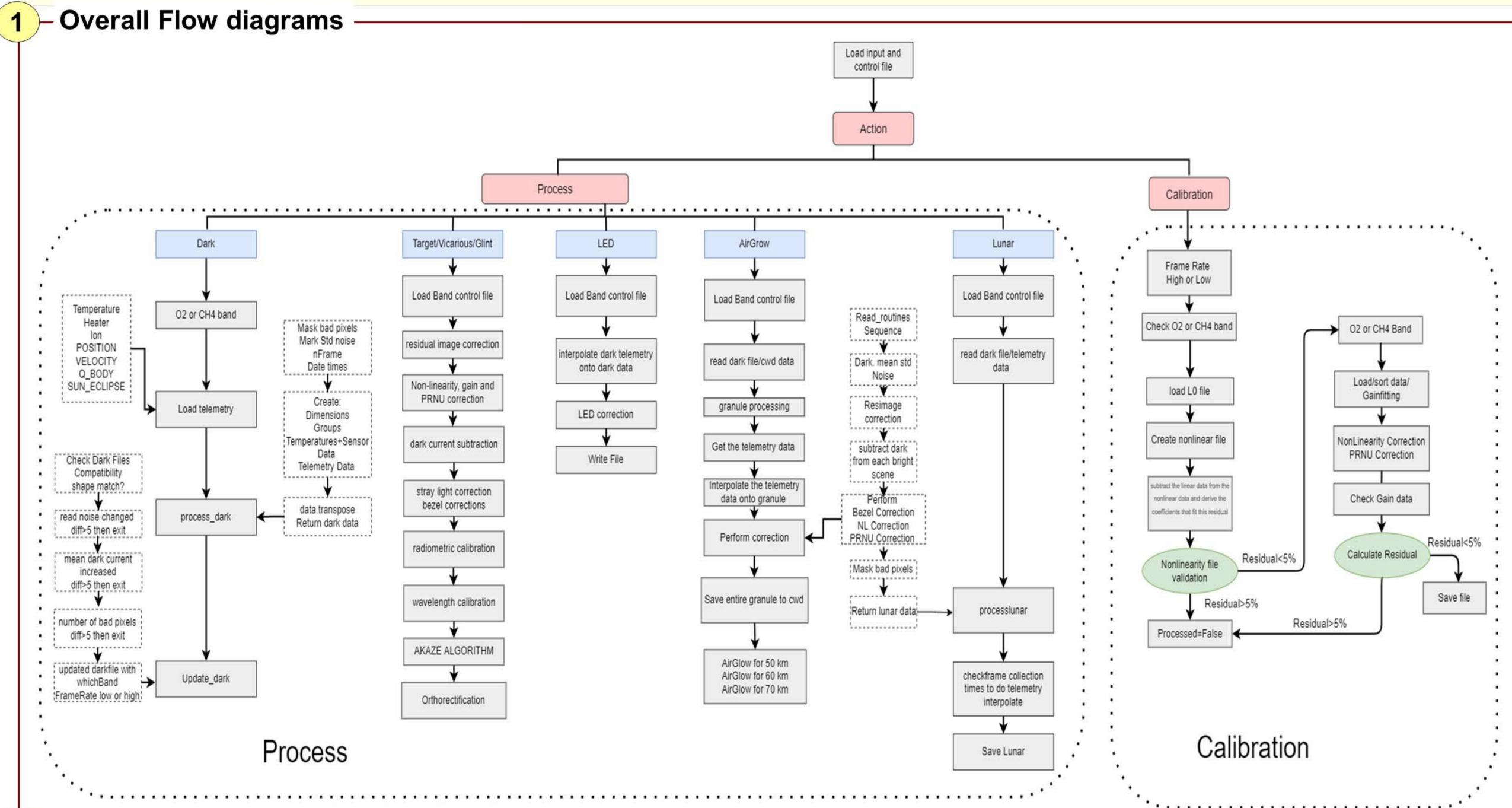
Development of the MethaneSAT L0-1B processor

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Introduction

MethaneSAT is an Environmental Defense Fund (EDF) satellite mission set to launch in mid-2023 to monitor methane emission from over 80% of the oil and gas industry and other sources with high precision and fine spatial resolution. The MethaneSAT instrument consists of two push-broom imaging spectrometers: the CH4 spectrometer (1.598-1.676 μm) to detect CH4 and CO2 absorption near 1.65 and 1.61 μm, and the O2 spectrometer (1.249-1.305μm) to detect O2 absorption near 1.27 μm. It is currently being built by Ball Aerospace and under sensor-level testing. Integration with the spacecraft bus by Blue Canyon Technologies will occur in Q3 2022 followed by flight-system level testing. MethaneAIR is the airborne simulator for MethaneSAT. It was successfully deployed in July/August 2021 aboard the NSF/NCAR Gulfstream V and produced ~50 hours of observations. A L0-1b processor has been developed for MethaneAIR to convert digital counts to radiometrically, spectrally, and geometrically calibrated L1b radiance spectra. The MethaneSAT L0-1b processor is being developed leveraging that the MethaneAIR L0-1b processor and analysis of MethaneSAT instrument calibration test data.



2 - Input Maps

- 1. Snow/Ice and Earth Orientation Parameters Northern hemisphere: 1 km resolution data from U.S. National Ice Center Southern hemisphere: NOAA Global Multisensor Automated Snow/Ice Cover Map (GMASI) global snow/ice/land mask.
- 2. Digital Elevation Map Fixed Map

The digital elevation map (DEM) includes ALOS World 3D-30m (AW3D30) global digital surface model (DSM)

3. MODIS Land Type Tagging - Terra and Aqua combined Moderate Resolution Imaging Spectroradiometer (MODIS) Land Cover Type (MCD12Q1) Version 6 data product provides global land cover types at yearly intervals



3 Five major parts

This design assumes that the system will be running in Flyte, which will be responsible for the orchestration and triggering as well as managing various specific aspects.

- 1. Sorting between calibration and science target L0 files
- 2. L0 to L1a processing Apply corrections to the data (e.g. bad pixels, dark current subtraction, stray light, residual image correction, non-linearity, gain and PRNU correction after Bezel correction, etc).
- 3. L1a to L1b processing Apply orthorectification algorithms, do the wavelength Calibration
- 4. GeoAkaze Adjustment/Correction Retry frames that failed
 orthorectification using successful,
 neighboring frames as input.
- 5. GeoTagging & Output collection Tag the L1b with relevant information such as surface conditions using L1b geo data as reference.

4 On-orbit calibration algorithms —

The On-oribit calibration algorithms:

- 1. Dark current measurements: update bad pixel map, random telegram signal (RTS) map, monitor dark current level and its temperature dependence
- 2. LED measurements: apply photon transfer to monitor gain, non-linearity, and PRNU.
- 3. Radiometric calibration trending: use vicarious calibration and/or lunar measurements
- 4. Wavelength shift and ISRF monitoring: using wavelength calibration & airglow results

5 Outputs

- 1. Geolocation info: Longitude, Latitude, CornerLongitude/Latitude, ViewingZenithAngle, , ViewingAzimuthAngle, RelativeAzimuthAngle, Surface/ObservationAltitude, Time, AircraftLongitude/Latitude, Aircraft Altitude and PixelBore
- 2. LandType, SnowIceTag, EclipseFlags
- 3. Band: Wavelength, Radiance, Signal to noise ratio, RadianceFlag

6 - Affiliations & Acknowledgements

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