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Campaign flown on NASA DC-8, carrying:

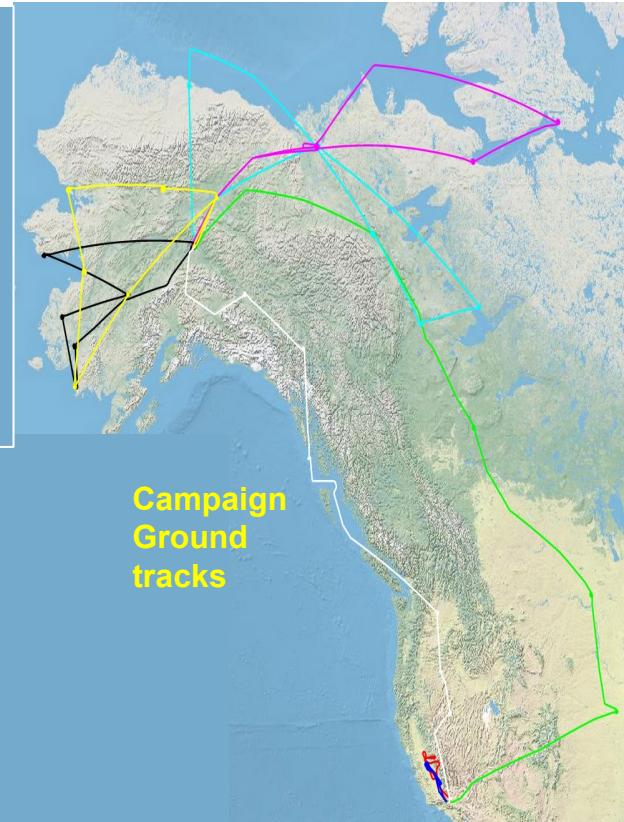
- Goddard CO₂ Sounder Lidar
- Goddard Picarro, *in situ*
- LaRC AVOCET, *in situ*
- LaRC DLH, *in situ*



- 8 flights
- July 20- Aug 8, 2017
- 55 hours of airborne measurements
- Comparison with *in situ* at 47 locations

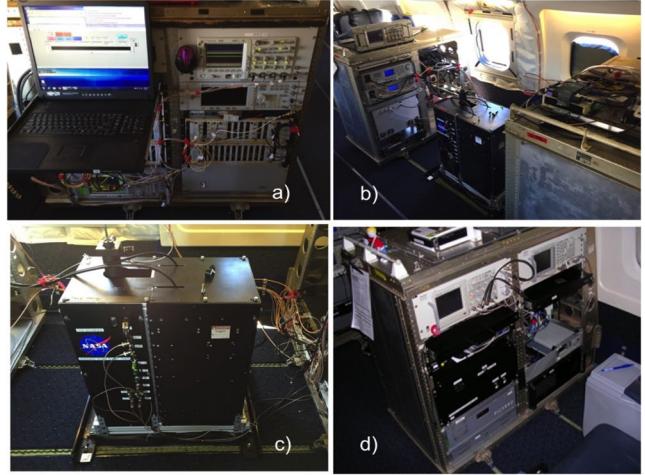
Introduction

- Pulsed IPDA lidar measurements of XCO₂ over long flight lines
- Lidar measurements of XCO₂ in Arctic, for first time
- Measurements made in diverse set of atmospheric & surface conditions
- Analysis of XCO₂ measurements showed:
 - Gradients in XCO₂: North-south, East-west & Locally
 - Local features in XCO₂, including one caused by wildfires
 - Vertically resolved aerosol scattering profiles



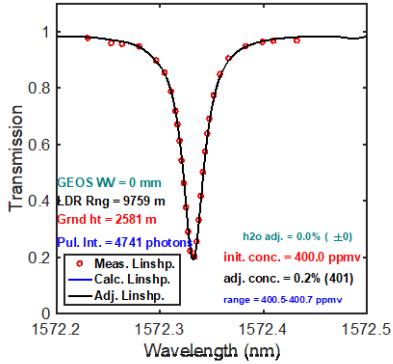
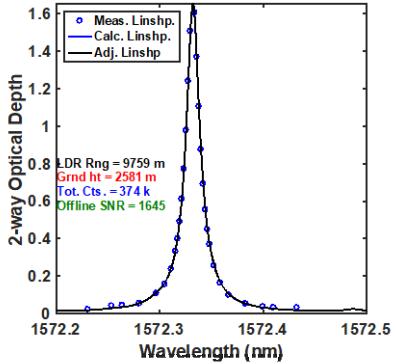
Spiral-down maneuvers allowed assessment of measurement “bias”

CO₂ Sounder Lidar & other campaign instruments

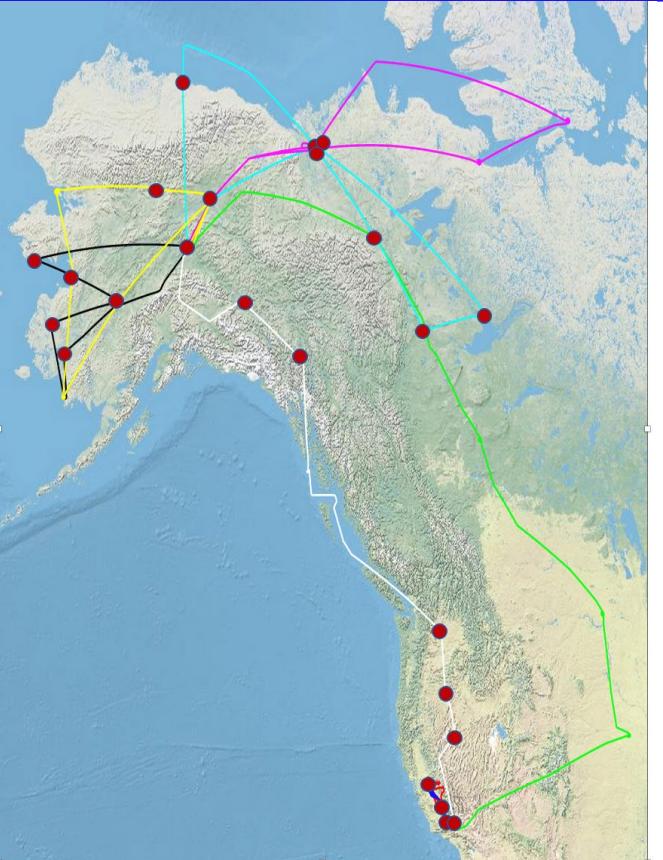


Other science instruments on 2017 campaign

- **Picarro** (Randy Kawa) – in situ CO₂ and WV
- **AVOCET** (Josh DiGangi/LaRC) – in situ CO₂, CH₄, CO
- **DLH** (Glenn Diskin/LaRC) – in situ WV
- **ACES** (Mike Obland/LaRC) – IPDA lidar to measure XCO₂ using line near 1571 nm. Uses modulated CW lasers at 3 wavelengths



- Direct Detection IPDA lidar - emits 10 kHz train of laser pulses
- Measures column CO₂ absorption using 1572.33 nm line.
- Laser pulses - stepped in 30 wavelengths across line; ~300 scans/sec
- Time resolved receiver, HgCdTe APD detector
- Measures backscatter profile, range & samples of CO₂ line shape
- XCO₂ Retrievals (Sun et al, AMT 2021):
 - Line shape samples, range to scattering surface
 - Atmospheric state (DC-8 measurements or GEOS-5)
 - CO₂ Spectroscopy: HITRAN 2008, Lamouroux 2010 line mixing



2017 ASCENDS Airborne Campaign

37 Spiral locations selected for comparison of Lidar XCO₂ vs in situ XCO₂

Bias =
Lidar – in situ in upper 2 km of
each spiral

For each spiral, used 3 different
approaches to correct for lidar
receiver's spectral non-uniformity:

- Linear
- Nonlinear (quadratic)
- Shifted BPF

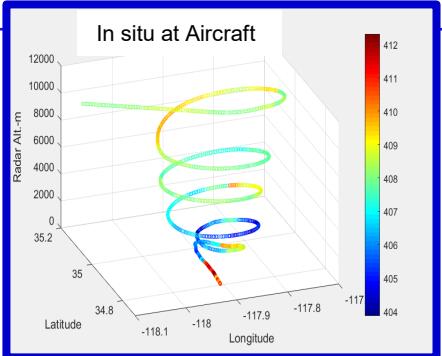
Notation for each spiral:

- **Bold** – lowest bias
- **Red**: highest bias

2017 Spiral Analysis (Lidar Avocet)					
Ave of top 2 1-km alts					
Flight Month/Day	Spiral	Spiral #	Ave Alt linear	Ave Alt Nonlinear	Ave alt BPF shifted 30 pm
720	Cas1	1			
720	Cas2	2			
720	Edw	3			
		4			
721	Cas1	5			
721	Port1	6			
721	Cas2	7			
721	Port2	8			
721	Cas3	9			
		10			
722	Grandsland	11			
722	Minnott	12			
722	LoonRiv	13			
		14			
731	Inuvik	15			
731	NormW	16			
731	FortSimp	17			
731	Yellowkn	18			
731	Inuvik2	19			
731	Deadhorse	20			
		21			
802	Inuvik1	22			
802	Kugluktuk	23			
802	CambridgeB	24			
802	Inuvik2	25			
		26			
805	Bethel	27			
805	Name	28			
805	St Marys	29			
805	McGrath	30			
805	Fairbanks	31			
		32			
806	Bettles	33			
806	Kotzebue	34			
806	Unalakleet	35			
806	McGrath	36			
806	PointT	37			
		38			
808	Northway	39			
808	Whitehorse	40			
808	Moosonee	41			
808	Wildhorse	42			
808	Winnemucca	43			
808	Edwards	44			
		Mean diff for campaign	Mean diff for campaign	Mean diff for campaign	
For campaign	Count				
# of spirals	37	0.78	-0.15	0.31	
		Std Dev of Means	Std Dev of Means	Std Dev of Means	
		0.50	0.44	0.50	

Sample Airborne Measurements made in 2017

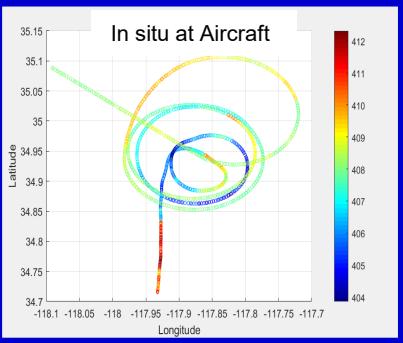
July 20 Spiral over Edwards CA: CO₂ & XCO₂ Retrievals



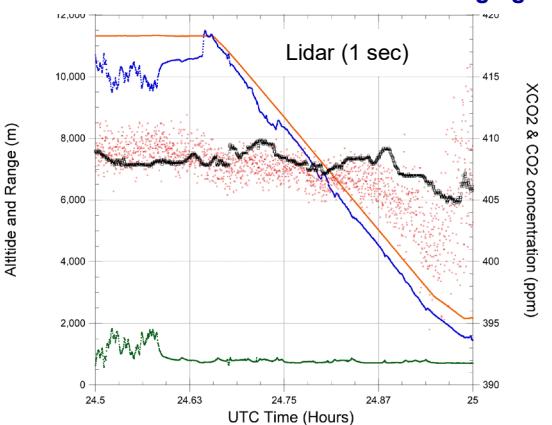
Picarro (in situ) CO₂ measurements at aircraft made during spiral

<- Side view

Top view->



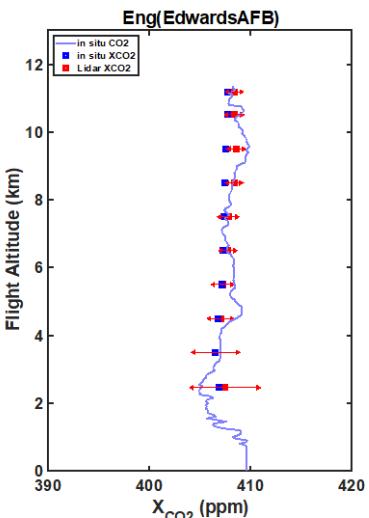
Red dots: XCO₂ from CO₂ Sounder Lidar
 Black dots: CO₂ (at altitude) from in situ
 All XCO₂ Retrievals use 1 second averaging time



Comparison of XCO₂ measurements:
 • Red – lidar
 • Blue dots - In situ, ave'd to surface

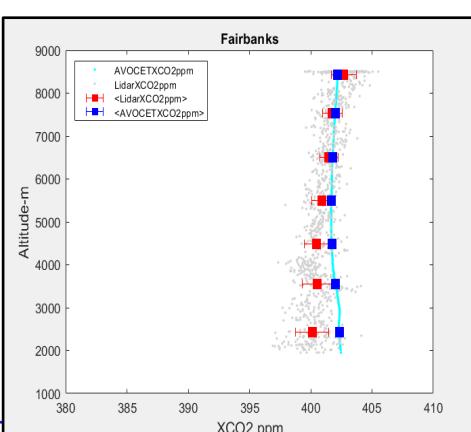
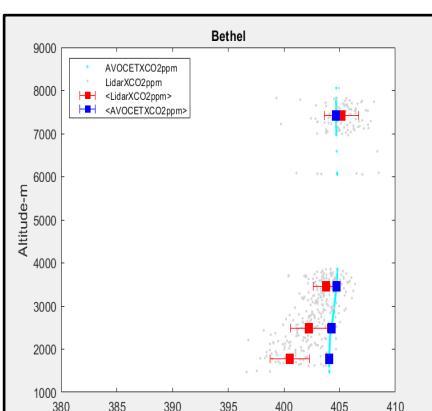
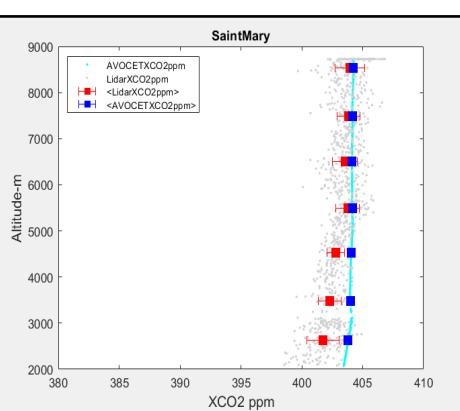
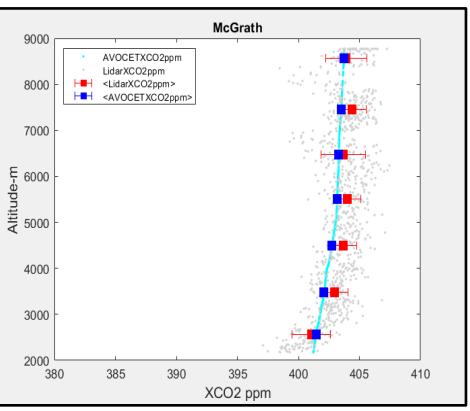
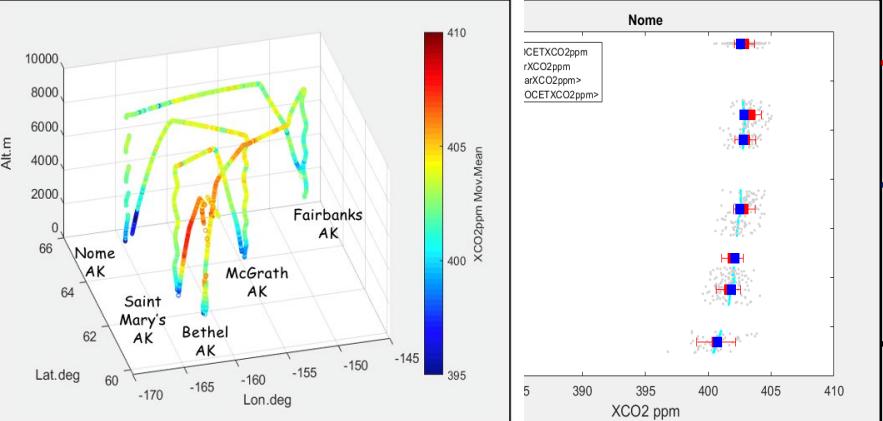
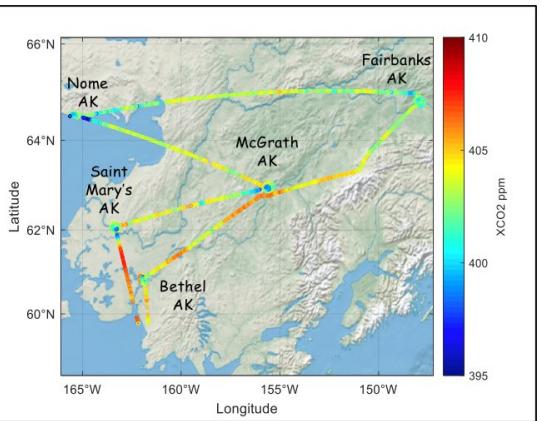
Reference atmosphere (LUT)
 for XCO₂ retrievals based on:
 DC-8 T & P
 PICARRO WV

Lidar retrievals use 1
 second averaging time



Lidar XCO₂ vs *in situ* XCO₂ in Spirals

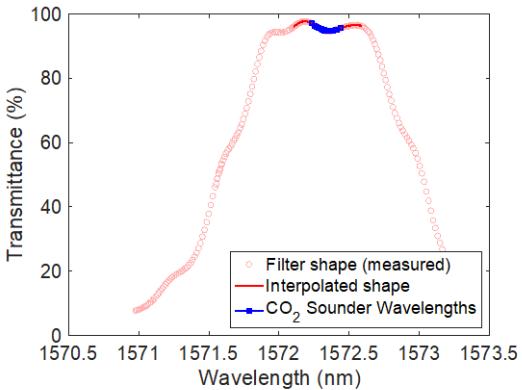
(for Aug 5, 2017 flight in Alaska)



Where:

- **Red:** Lidar 1-sec retrievals in 1 km vertical bins
(mean +/- 1 std dev)
 - **Blue dots** – Column XCO₂ from AVOCET using lidar vertical weighting function
- For this flight:**
- **< 0.5 ppm difference between Lidar & *in situ* XCO₂ at altitudes > 4 km**

Lidar receiver has spectral bandpass filter to reject sunlight



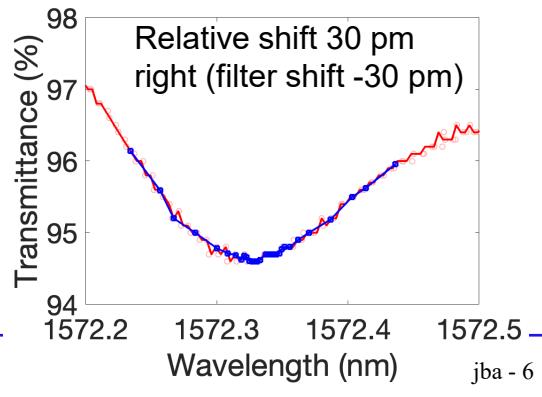
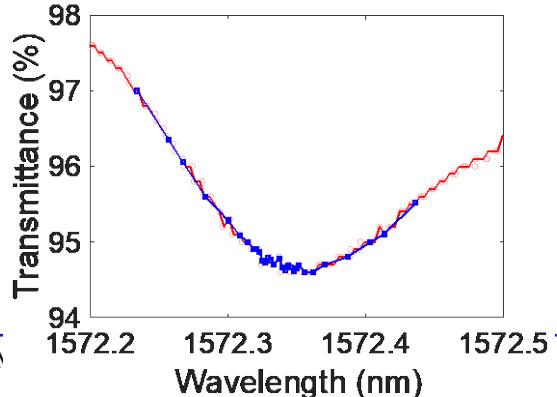
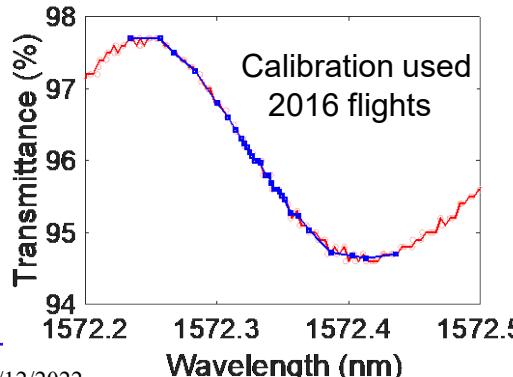
- An ideal filter has exactly same transmission at all laser wavelengths
- Ours used in 2017 had a few % variability
- This slightly distorted the lidar measured CO_2 line shape & caused bias in retrieval

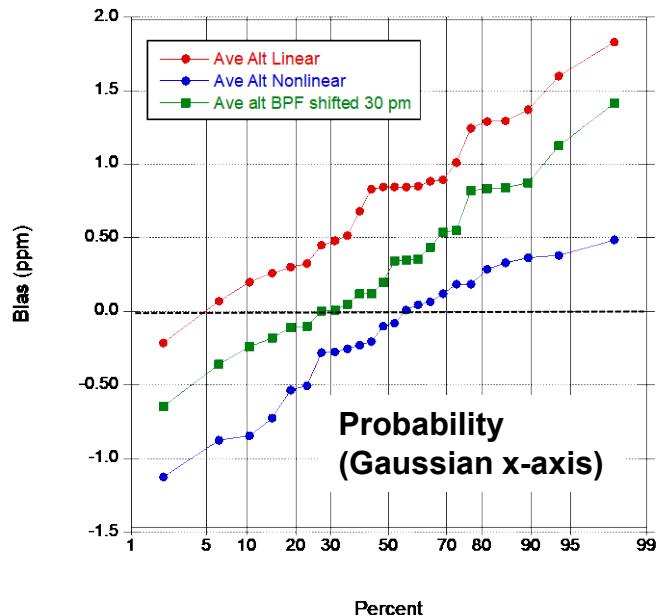
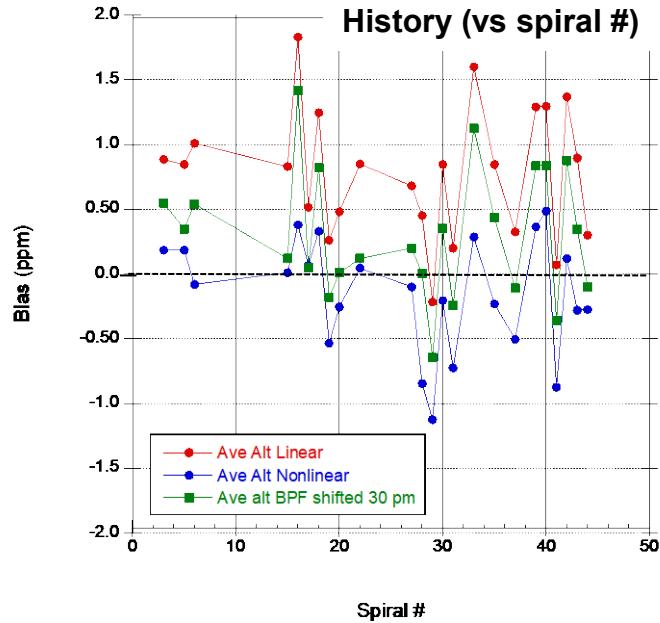
Our present Line fitting Retrieval allows either:

1. Correcting for linear slope
2. Correcting for quadratic shape
3. Shift filter in wavelength (done manually) & use linear correction

Improved approaches are practical for the future

Expanded view of Lidar's 2017 Bandpass Filter peak (red) & lidar wavelengths (blue)





Bias Statistics for Campaign (ppm)

Linear Nonlinear Shifted BPF

Mean diff for campaign	Mean diff for campaign	Mean diff for campaign
0.78	-0.15	0.31
Std Dev of Means	0.44	0.50

- The + & – changes in bias (ie bias excursions) are well correlated for different line-fitting wavelength corrections
=> Deviations driven by factors not related to wavelength correction approach
- Linear fit correction has largest + excursions
- Distributions appear roughly gaussian

Summary

- The ASCENDS/ABoVE airborne campaign had 8 flights in July and August 2017.
 - 47 spiral-down maneuvers: California, NWT Canada, Arctic Ocean, Alaska, transit flights
- Performed analysis of “Bias” [XCO_2 (lidar) – (XCO_2 (in situ))] in 37 of these spirals.
- “Bias” values & statistics depended on correction for non-uniform spectral transmission in lidar receiver.
 - Using a quadratic line fit correction: lowest average bias for campaign.
 - Mean value of bias for campaign: -0.15 ppm, std. dev for campaign: 0.44 ppm
- Approaches to further reduce bias in updates to CO_2 Sounder lidar & in space version:
 - Better synchronize & check time stamps on in-situ & aircraft data sets
 - Any time offsets in 3 different data streams used cause data shifts -> “Bias”
 - Change receiver’s optical bandpass filter to one with flatter top (less wavelength variability)
 - Sample outgoing laser energy through receiver’s optical filter (processing normalizes variability)

Questions or comments: – Please email: james.b.abshire@nasa.gov